

# *Automata Modeling of Quorum Sensing for Nanocommunication Networks*

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Automata Modeling of Quorum Sensing for Nanocommunication Networks  
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## *Table of Contents*

- Introduction
- Quorum Sensing
- Automata Modeling of Quorum Sensing Bacteria
- Nanomachine Design Based on Quorum Sensing Bacteria
- Concluding Remarks

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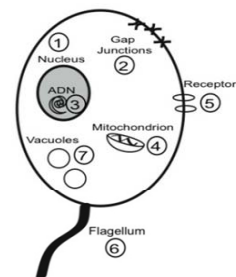
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## Introduction: Nanotechnology and Nanomachines



I. F. Akyildiz, F. Brunetti, and C. Blázquez, "*Nanonetworking: A New Communication Paradigm*,"  
Computer Networks (Elsevier) Journal, Vol. 52, pp. 2260-2279, August, 2008.

- **Nanotechnology** is enabling the development of devices in a scale ranging from one to a few hundred nanometers.
- A **nanomachine** is the most basic functional unit, which is consisting of nanoscale components and which is able to perform a specific task at nano-level, such as computing, data storing, sensing or actuation.



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## Introduction: Interaction between Nanomachines



### WHY?

Due to the reduced size of the nanomachines, their limitations are clear:

- Range
- Complexity

NaNoNetworks expand the possibilities of nanomachines, increasing the complexity and range of operation of the system.

### HOW?

- Molecular Communication

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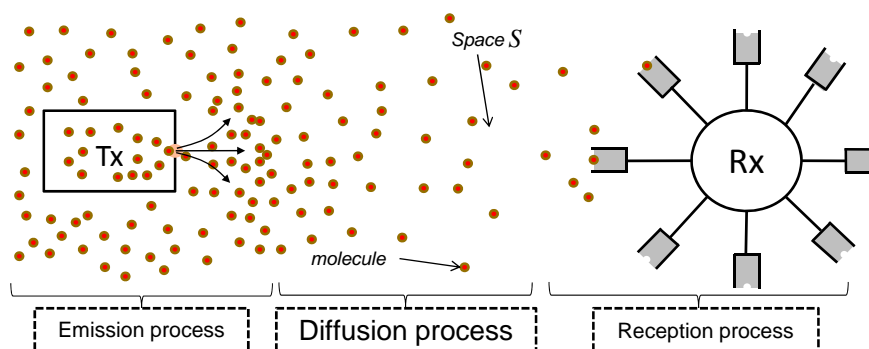
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## Introduction: Molecular Communication (I)



- I. F. Akyildiz, F. Brunetti, and C. Blázquez, "**Nanonetworking: A New Communication Paradigm**," Computer Networks (Elsevier) Journal, Vol. 52, pp. 2260-2279, August, 2008.
- M. Pierobon, I. F. Akyildiz, "**A Physical End-to-End Model for Molecular Communication in Nanonetworks**," IEEE Journal of Selected Areas in Communications (JSAC), May 2010.

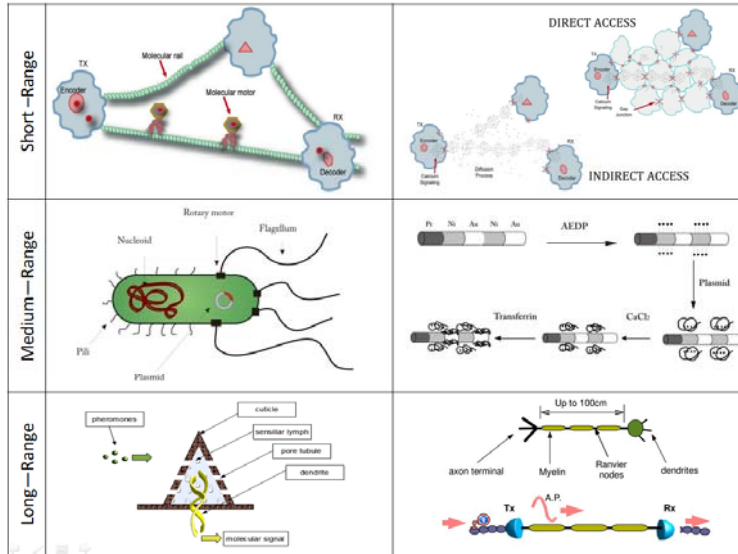


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## Introduction: Molecular Communication (II)



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## Quorum Sensing



J. Henke and B. Bassler, "Bacterial social engagements," *Trends in Cell Biology*, vol. 14, 2004, pp. 648-656.



### What?

Quorum Sensing is a mechanism used by bacteria to coordinate their behavior in a colony, as a function of their population.

### Why?

Processes controlled by Quorum Sensing are unproductive when undertaken by an individual bacterium but become effective when undertaken by the group.

### How?

Quorum Sensing is achieved through the production, release, and subsequent detection of and response to a threshold concentration of **autoinducers**.

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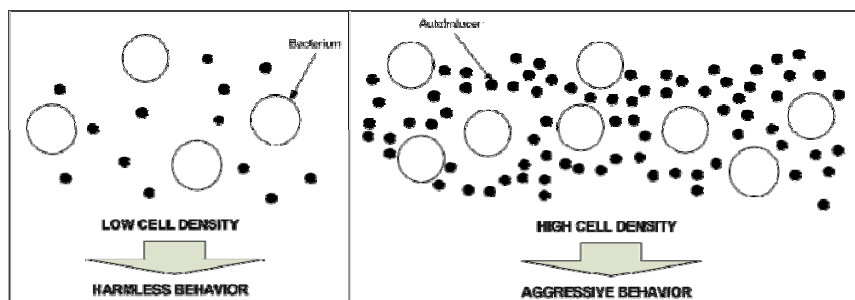
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## Quorum Sensing: Principles and Mechanisms (I)



- When the population of bacteria grows, the extracellular concentration of autoinducers increases as well.
- If this concentration reaches the activation threshold, it means that a certain population has been achieved, and the group responds to it with a population-wide change of behavior.



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## Quorum Sensing: Principles and Mechanisms (II)



- Autoinducers are the key of the process.
- Tiny molecules (smaller than 1nm) that trigger an autocatalytic reaction: trigger the release of more particles of the same kind.
- There is a vast variety of autoinducers, enabling:
  - **Intraspecies communication:** when only bacteria of one species is able to receive that autoinducer.
  - **Interspecies communication:** when chemosensors of many species of bacteria are able to sense that autoinducer (*LuxS*).

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## Quorum Sensing: Complex Systems



- Some bacteria count on more than one Quorum Sensing system.
- For instance, *vibrio harveyi* bacteria activate only with the presence of two different types of autoinducers at the same time.
- Nanomachines can mimick this feature to achieve a higher level of complexity.

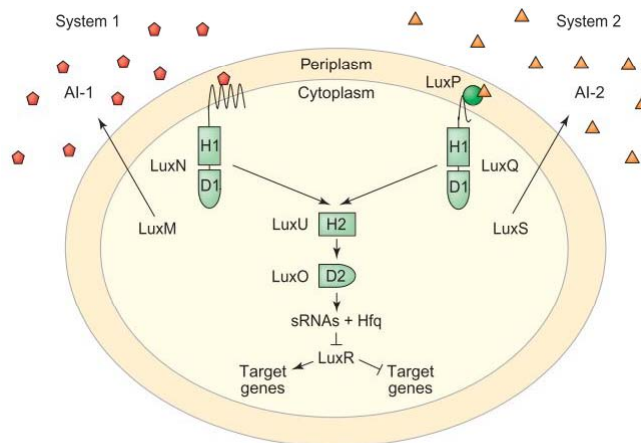
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## Quorum Sensing: Complex Systems (II)

J. Henke and B. Bassler, "Bacterial social engagements," *Trends in Cell Biology*, vol. 14, 2004, pp. 648-656.



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## Quorum Sensing: Communication Aspects



- Quorum Sensing is a special case of Molecular Communication.
- All bacteria are transmitters and receivers.
- The message is collective, modulated by the concentration of autoinducers in the environment.
- The message is encoded in the chemical composition of those autoinducers.

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## Automata Modeling: Motivation



- The need for a functional model of Quorum Sensing bacteria (not biological model).
- The need for a model that integrates Quorum Sensing and the behavior after reaching quorum.
- The need for a model easily implementable to use it in future nanomachines and coordinate their actions.

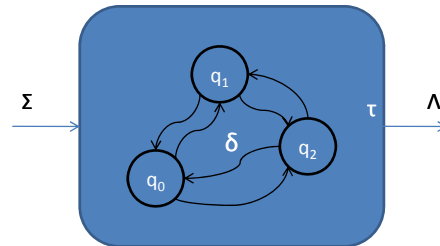


## Automata Modeling: Definitions



• A Moore machine is a Finite State Machine represented by the six-tuple  $\{Q, \Sigma, \Lambda, \delta, \tau, q_0\}$ .

- $Q$ : finite set of internal states.
- $\Sigma$ : finite alphabet of inputs.
- $\Lambda$ : finite alphabet of outputs.
- $\delta$ : transition function.
- $\tau$ : output function.
- $q_0$ : initial state.



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## Automata Modeling of Quorum Sensing Bacteria (I)



• The alphabet of inputs maps different levels of concentration of autoinducers sensed by the bacteria.  $\Sigma$

• The alphabet of outputs models different signals that modify the emission of autoinducers, mainly.  $\Lambda$

• We will divide the model in two parts:

- **Pre-Quorum section:** in which the bacteria have not reached the critical population to activate.
- **Post-Quorum section:** after reaching quorum, bacteria activate their “aggressive” behavior.

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## PRE-QUORUM SECTION

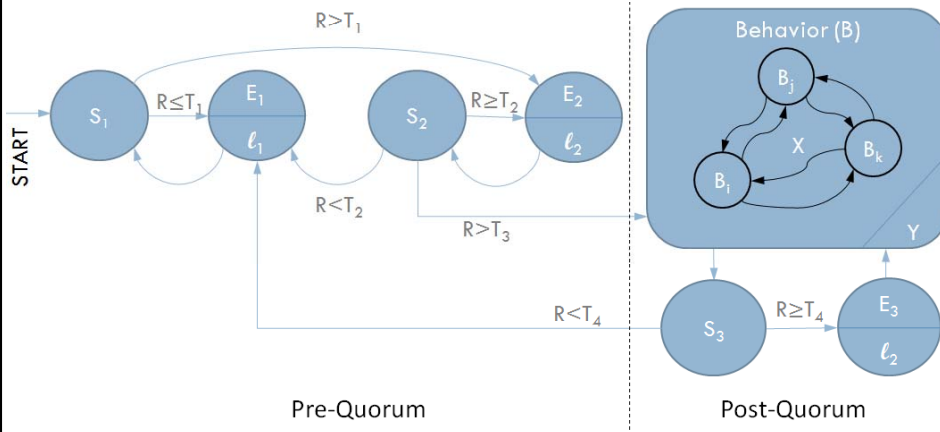
- In the pre-quorum section the bacteria:
  - **Sense the environment:** in order to know the concentration of autoinducers. (*S states*)
  - **Emit autoinducers:** in order to let the other bacteria be aware of one's presence. (*E states*)
- The emission of autoinducers depends on the amount sensed.
  - **Basal rate.** (*state E1, output y1*)
  - **Autocatalytic rate.** (*state E2, output y2*)
- The transitions are selected based on that dependence, leaving the section when the activation threshold is surpassed.



## POST-QUORUM SECTION

- In the post-quorum section the bacteria:
  - **Activate their collective behavior.** (*B states*)
  - **Sense the environment** (*S state*)
  - **Emit autoinducers.** (*E state*)
- The collective behavior has to be modeled for each case (e.g. virulence, bioluminescence).
- Sensing and emission states help to deactivate the new behavior if the population falls.

**COMPLETE MODEL**



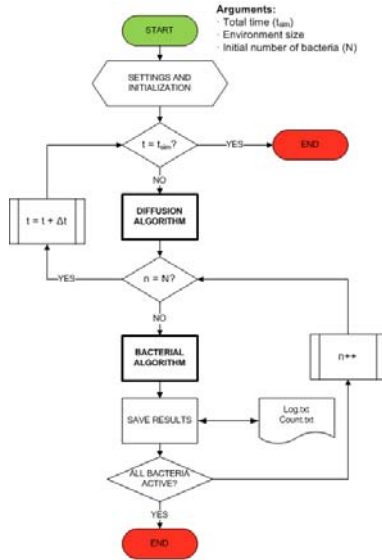
- The diffusion of autoinducers in the environment is a key factor in Quorum Sensing.
- It is modeled following Fick's second law:

$$\frac{\partial c(\bar{x}, t)}{\partial t} = D \nabla^2 c(\bar{x}, t)$$

- To implement it, we need apply the finite differences method:

$$\frac{c(\bar{x}, t + \Delta t) - c(\bar{x}, t)}{\Delta t} = D \frac{c(\bar{x} - \Delta \bar{x}, t) - 2c(\bar{x}, t) + c(\bar{x} + \Delta \bar{x}, t)}{(\Delta \bar{x})^2}$$

## Simulations of Quorum Sensing Bacteria (II)



### DIFFUSION ALGORITHM

- Implementation of second Fick's Law of diffusion.

### BACTERIAL ALGORITHM

- Implementation of the Moore machine presented + reproduction.

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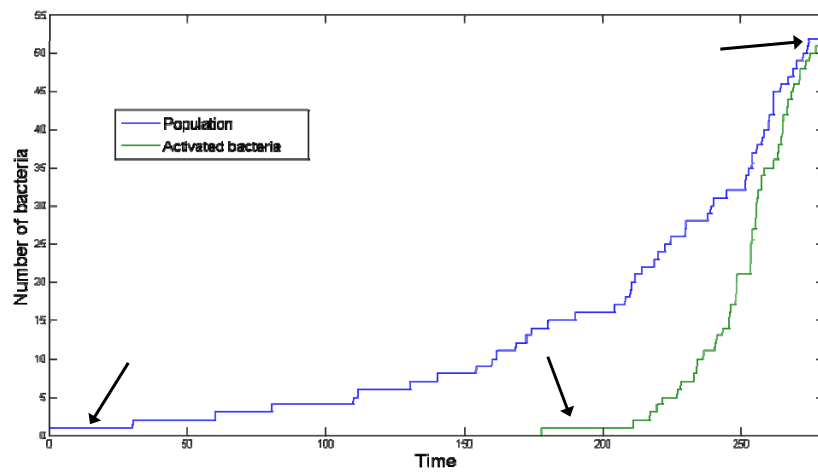
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## Results (I)



### VALIDATION

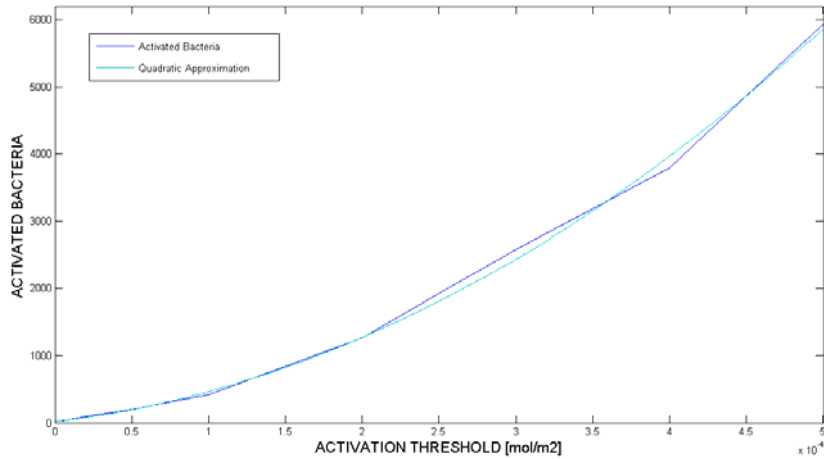


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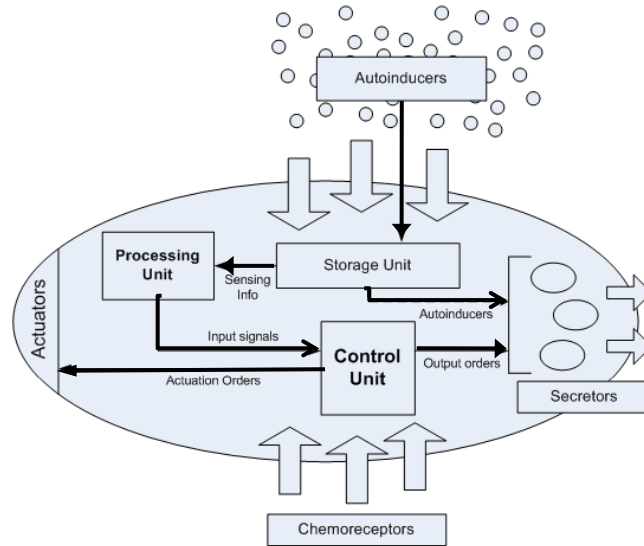
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## ACTIVATION THRESHOLD



- Introduction
- Quorum Sensing
- Automata Modeling of Quorum Sensing Bacteria
- **Nanomachine Design Based on Quorum Sensing Bacteria**
- Concluding Remarks

## Architecture for Quorum Nanomachines



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## Implementation of Quorum Nanomachines



- Collective Activity Synchronization
- Collective actuation after Localized Sensing

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## Collective Activity Synchronization

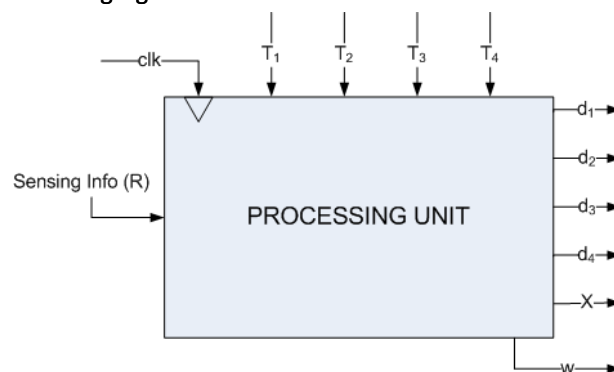
### Direct application of Quorum Sensing

- Tissue Repairing
- Drug Release

### Collective actuation after Localized Sensing

### The outputs of the PU are inputs of the CU:

- $d_{1-4}$ : comparison of the concentration sensed ( $R$ ) with different thresholds ( $T_{1-4}$ ).
- $w$ : waiting signal.



## Relaxation Time



- Bacteria have ways to differentiate their own autoinducers from autoinducers released by other individuals. Nanomachines do not.
- It is an important issue to avoid erroneous activations.
- Nanomachines **NEED TO WAIT** until their autoinducers diffuse away before sensing the environment again.
  - HOW?
    - With the wait signal.
  - HOW MUCH?
    - $t_{MIN} \approx \left(\frac{8\pi p}{3}\right)^{\frac{2}{3}} \frac{R^2}{4\pi D}$

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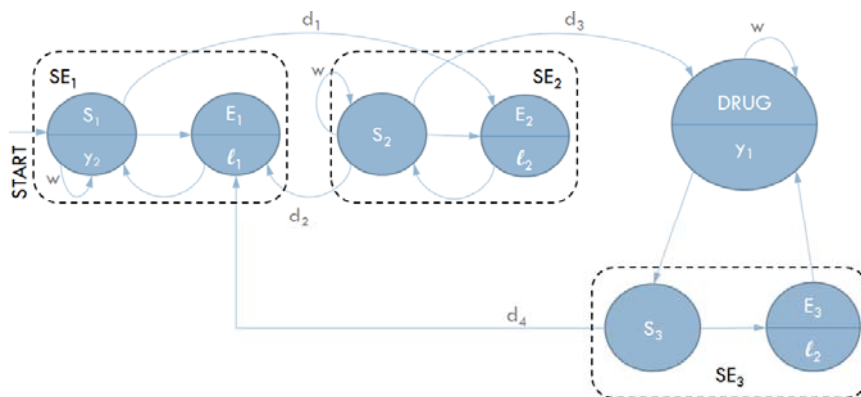
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## Collective Activity Synchronization: Control Unit



- **Modifications:**
  - Use of the waiting signal to implement relaxation time.
  - Post-Quorum states adapted to a specific case.



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## Collective Activity Synchronization: Simulations



### Several differences with the simulations involving bacteria:

- Deployment of a given number of nanomachines.
- No reproduction.
- Application of post-Quorum behavior.

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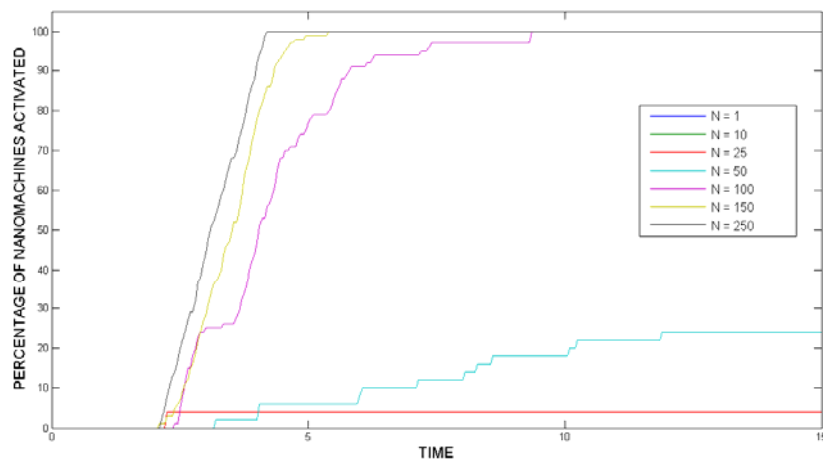
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## Collective Activity Synchronization: Results



### VALIDATION (pre-Quorum)



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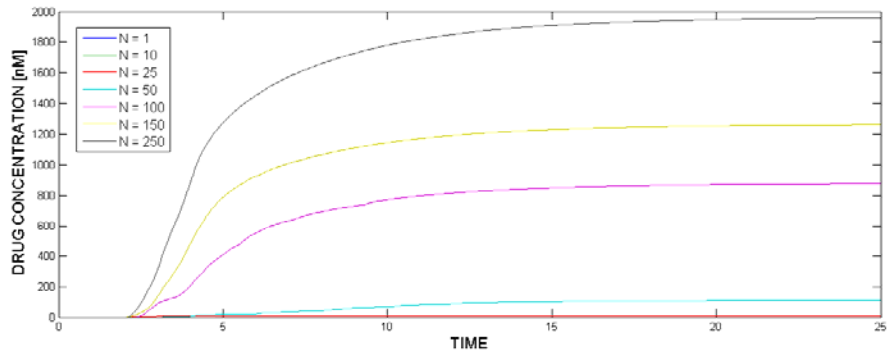
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## Collective Activity Synchronization: Results (II)



### VALIDATION (post-Quorum)



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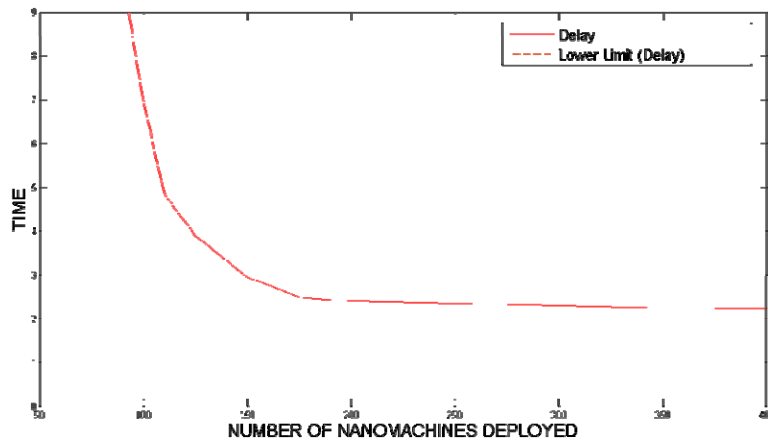
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## Collective Activity Synchronization: Results (III)



### DELAY OF ACTIVATION



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## Implementation of Quorum Nanomachines



- Collective Activity Synchronization
- **Collective Actuation after Localized Sensing**
  - Reaction to a certain localized event
    - Cancer Detection
    - Antibiotic purposes

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## Collective Actuation after Localized Sensing



- A cluster of nanomachines is deployed in the environment.
- Their behavior is as follows:
  - If at least one of the nanomachines senses a certain event, all of them must activate by means of Quorum Sensing.
  - If not, they must remain dormant.
- In the simulations, the concentration of a certain chemical will be monitored.

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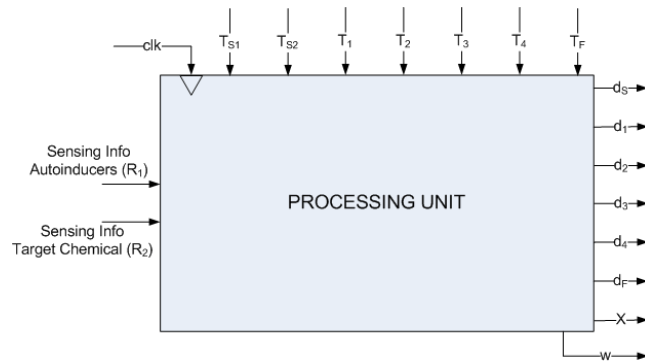
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Collective Actuation after Localized Sensing: Processing Unit



New thresholds and signals:

- $d_s$ : starting signal for Quorum Sensing  $R_1 > T_{s1} \ || \ R_2 > T_{s2}$
- $d_f$ : ending signal for the actuation  $R_2 < T_f$



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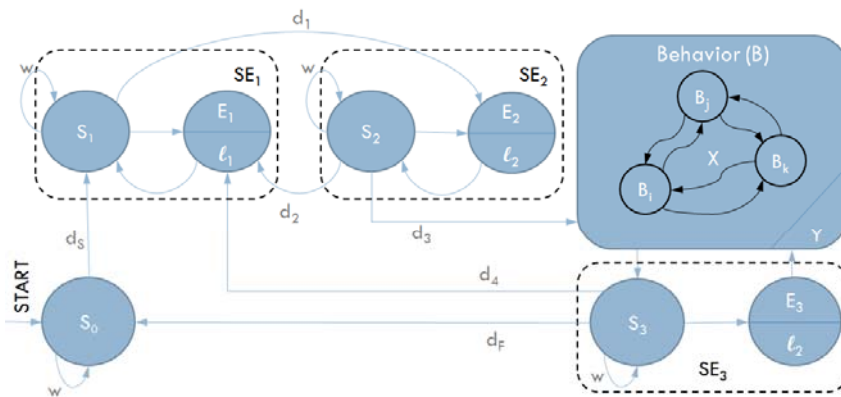
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Collective Actuation after Localized Sensing: Control Unit



Modifications:

- New initial state ( $S_0$ ), also called "dormant state".
- $d_s$  is the starting signal.



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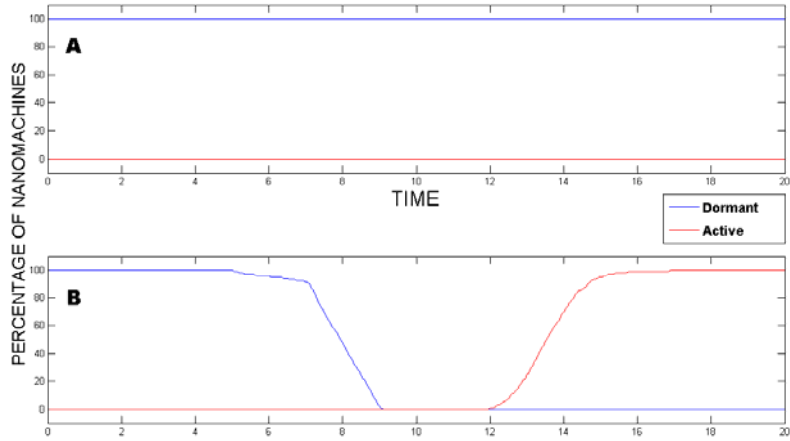
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## Collective Actuation after Localized Sensing: Results (I)



### VALIDATION



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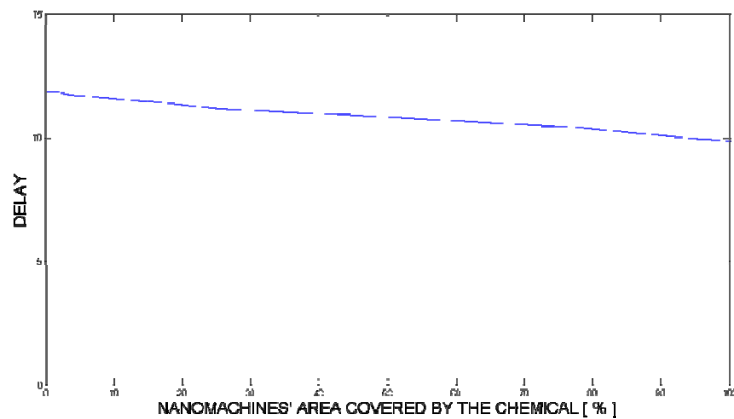
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## Collective Actuation after Localized Sensing: Results (II)



### DELAY OF ACTIVATION



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## Concluding Remarks



### ● Conclusions:

- Quorum Sensing can be used to coordinate or synchronize the action of nanomachines.
- An automata model has been presented and simulated for Quorum Sensing bacteria.
- This model can be used as the central control unit of nanomachines that perform Quorum Sensing.
- Two different implementations have been simulated and delay results have been extracted.

*Thank you!*



**Thank you very much for your attention.**

**Any question?**